

: 1.

:  
27.15.3085.00; ( ) / ; -  
01.85.0064903. - ., 1985. - 53 . 2. . . .  
. - 2010. - 3. - . 105 - 110. 3. X. .  
. - . - 1886. - 232 . 4.  
. - . - ., 1952. - 269 .

$i = M,$   
( " " . " , " , " )

### CALCULATION OF WORM GEARING PARAMETERS THE GENERAL SOLUTION

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**The Abstract:** The equations of a contact line and action surface of a worm gearing of a general view at which the surface of a worm thread is organised by a helical motion of any curve in a worm axial plane are obtained. That is caused by industrial necessity of software working out and CNC control data, for cutting of a worm and worm wheel by the universal tool.

**Keywords:** gearing, transmission, model, surface, worm, synthesis.

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**621.833**

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1.

, , , , , , , ,

[1],

[2] , . [3].  
 « »

, , ,

[4 - 7].

2.

, , , , , , ,

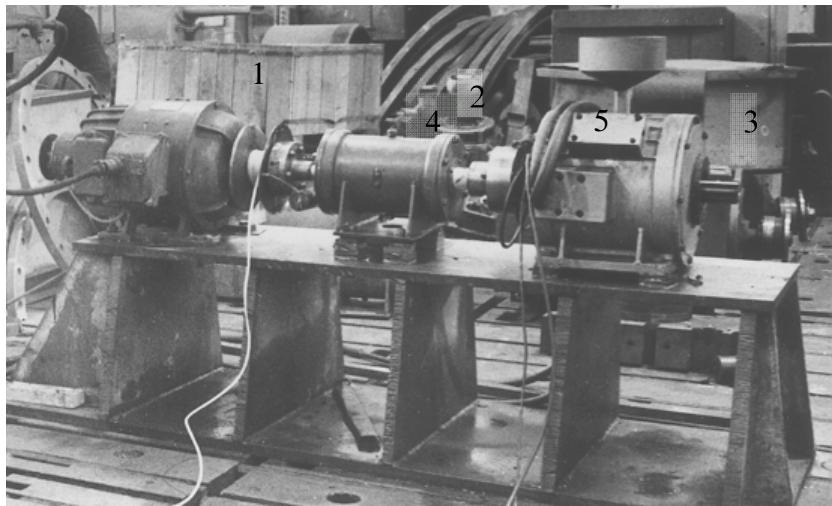
[8].

– 165 ( . 1) . 1.

1.

– 165

	I	II
	24	10
	25	10
	25	10
	24	1
,	14	25
,	7,25	14,2
,	7,25	14,2
,	158,68	130
.	164,65	130
,	157,5	126
,	164	134
,	65	40
,	3,3	
,	24	
,	1600	
,	1000	
,	525×230×280	
,	64	
( . 2),	4,8	
, /	10 ÷ 1500	
	,	
	– 20, – 22	
,	1,25	
	3	



- 165

2).

250- .

( .

2 ,

2.

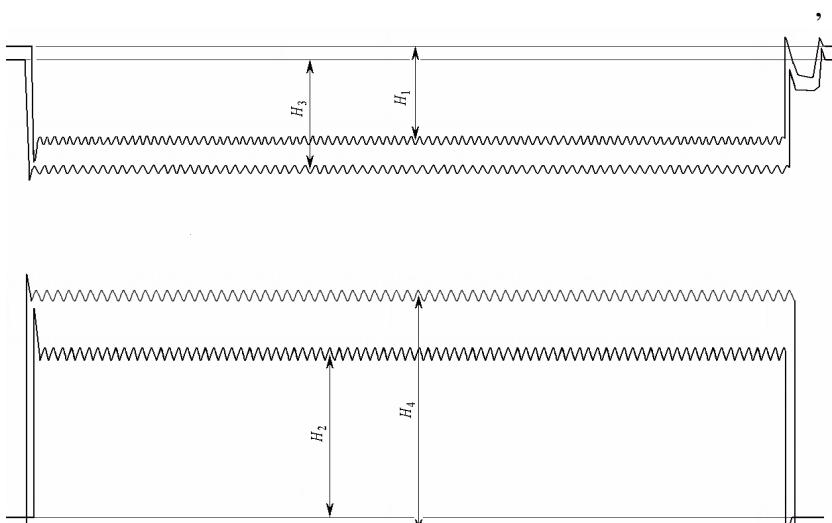
- 165: 1 -

; 2 -

-165; 3 -

; 4, 5 -

[9, 10].



0,765 / ,  $\beta_1 =$   
14,2 / . . .

1

0,765 14,2 ( . 3).

- 165

3

$$T_2 = 800$$

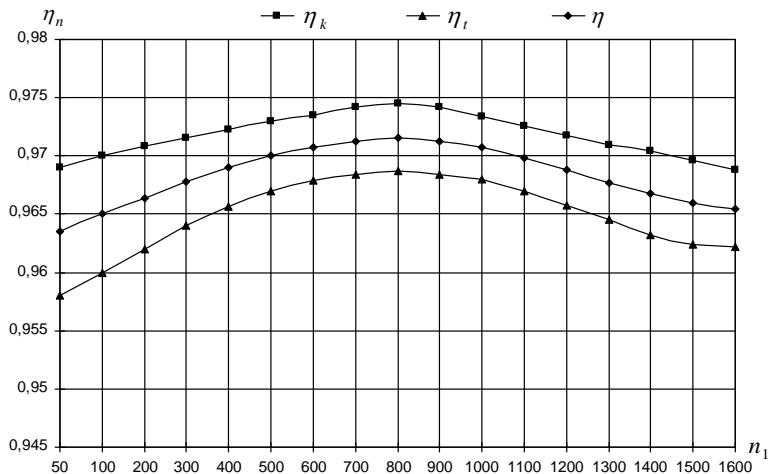
$$n_1 = 500 \quad / \quad : \quad H_1, \quad H_2 -$$

$$n_1 = \{100, 200, \dots, 1600\} \quad /$$

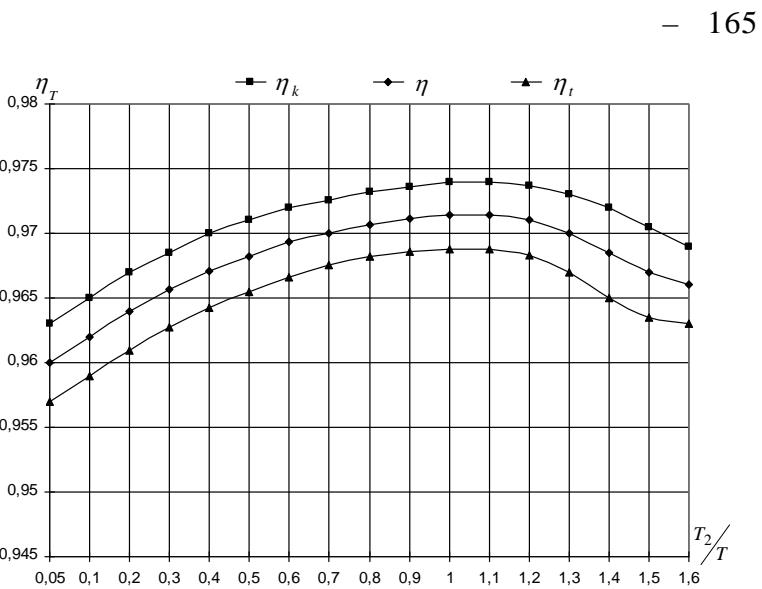
$$; \quad H_3, \quad H_4 -$$

$$T_2 = \{50; 100; 200; \dots; 1600\} \quad . \\ . 4 \quad . 5$$

- 165



1000



165

, n<sub>1</sub> = 800 / T<sub>2</sub>

(C = 0,54%).

60 2 14959-79

. 2.

2.

, %	Si	Mn	P	S	Cr	Ni	
	0,54	1,88	0,8	0,008	0,03	0,08	0,11
60 2 14959-79	0,57	1,5-2,0	0,6-9,9	0,035	0,035	0,3	

$$(\quad \cdot \cdot \quad ) \qquad (\quad \quad )$$

$$3 \quad (5 \div 7) \%$$

57 ÷ 63 HRC.

0,2

43 ÷ 48 HRC.

,

Ø15H7,

Ø14H7

1,5 .  
38 2 2

11-11 .

$$n_1 = 1500 \quad / \quad , \quad M_2 = 1500 \quad , \\ 2650 \quad .$$

- 165,

, 30 %

- 165

### 3.

$$\eta_{n_{\min}} = 0,964, \quad n_I \approx 800 \quad / \quad : \eta_{n_{\max}} = 0,972$$

$$n_{I_{\max}} = 1600 \quad / \quad : \eta_n = 0,965.$$

$$n_I = 800 \quad / \quad , \quad T_2 = 50 \quad : \quad \eta_{T_{\min}} = 0,96, \quad \eta_{T_{\max}} = 0,971$$

$$: T_2 = (1,0 \cdots 1,1)$$

$$T_2 = 1,6$$

$$\eta_T = 0,966.$$

$$n_I$$

$$2$$

$$n_I \quad [50 \dots 1600] \quad / \quad : \Delta \eta_n = 0,8\%.$$

$$[50 \dots 1600] \quad , (n_I = const),$$

$$\eta_{T_{\max}} \quad : \Delta \eta_T = 1,1\%.$$

$$n_I \quad n_I \approx 800$$

$$/ \quad ,$$

$$n_I,$$

$$(T_2 > T_{2c})$$

: 1. Kegelplanetengetriebe mit geräuscharm konzipierter Verzahnung. Maschinenmarkt 2005, 38, . 93. 2.

$$i \quad \dots : ( \quad i \dots , \dots , \dots )$$

i

## **RESEARCH OF EFFICIENCY AND RESOURCE PROTOTYPE gearbox WITH INTERMEDIATE ROLLING BODY**

*Strelnikov Y. V. (East Ukrainian National University, Ukraine)*

**The Abstract.** The experimental researches efficiency of gearbox with intermediate rolling bodies depending on an input shaft rotational speed and output shaft torque are presented. Results of resource prototypes of the specified gearboxes are stated. By results of the executed researches recommendations about perfecting of a construction of gearboxes with intermediate rolling bodies are offered.

**Keywords:** gearbox, the stand, roll, resistive-strain sensor, loading.

18.01.2011.